

Thermal Protector from Texas Instruments **Three-phase Manual or Automatic** Reset Types MY, MW, CY, CW and BY

Provides protection against overheating from all running and stalled rotor conditions including:

- Single-phasing
- Plugging duty
- Stalling or failure to start
- Heavy overloads
- High ambient
- Ventilation failures



Automatic reset round base

Manual reset

The protector consists of a molded phenolic bass assembly containing three heaters and a Klixon snap-acting thermal disc with three contacts. The Klixon disc is the neutral point of the motor. Each heater is in series with one of the phase windings of the motor, as well as with one of the contacts on the thermal disc. When the disc snaps open because of overheating, the netural of the motor is open circuited, thereby shutting down the motor. Dual voltage motors are protected with a single protector, as shown in the wiring diagrams.

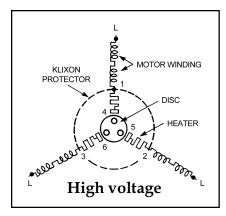
Mounting

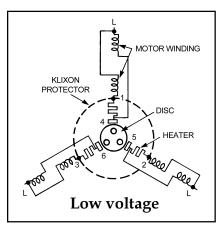
The protector should be located in the motor so that it will receive the maximum amount of heating from the windings, not only for running but also for stalled rotor conditions. The degree of protection obtained depends to a large extent on the protector location and its manner of mounting. The best location depends upon the construction of the motor; but in general, may be the air-sheild, endbell or possibly the stator iron. Preferably it should be in the discharge unit.

Engineering Samples

Provide the following information when requesting engineering samples:

- 1. Motor Horsepower
- 2. Voltage...single or dual
- 3. Amperes necessary to raise the motor windings to a stable temperature condition of approximately 130°C for class A, 155°C for class B in 25 C room ambient.
- 4. The temperature of the protector location iron and the temperature of the protector location air when the motor is stable under above (3) conditions.
- 5. The locked rotor amperage and time for windings to reach 125°C and 150°C from a 25°C room ambient.
- 6. Voltage of test.





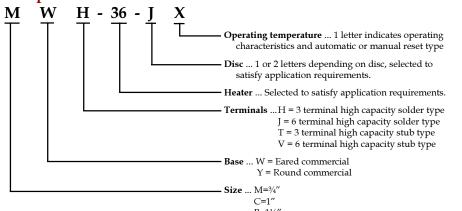
	Protector Types, Sizes and Estimated Horsepower Range									
or		ower	e Max Current							
Protector	Size	Horsepower	Voltage	220V	440V					
MY	3⁄4	^{1/8} -1 ¹ / ₂	220/440V	37	28					
MW	3⁄4	^{1/8} -1½	220/440V	37	28					
CY	1	1-3	220/440V	60	45					
CW	1	1-3	220/440V	60	45					
BY	11/4	2-7½	220/440V	125	75					

For dual voltage motors the higher voltage should be used for making the protector application and the lower voltage for selecting the size of the protector based on contact capacity. Because of the many various motor characteristics, a different size Klixon Protector than those indicated int he table above may be necessary for a given horsepower rating.

Code Structure

The following "Sample Code" is an explanation of the type of code which appears on each Klixon three-phase protector. By using this code, it is possible to determine size, type of base, terminals, heater, disc and operating temperatures.

Sample Code



B=1¼" F=1^{5/8"}

UL Recognized - File E15962



DimMYMWCYCWBYA $1.031\pm.010$ $1.390\pm.015$ $1.312\pm.010$ $1.390\pm.015$ $1.640\pm.010$ B $.970\pm.006$ $.970\pm.006$ $1.218\pm.010$ $1.218\pm.010$ $1.555\pm.010$ C $.125\pm.005$ $.175\pm.010$ $.125\pm.005$ $.175\pm.010$ $.156\pm.010$ D $.926\pm.010$ $.896\pm.010$ $.926\pm.010$ $.926\pm.010$ $1.000\pm.010^{+}$ E max $.203$ $.203$ $.250$ $.312$ F $.450\pm.015$ $.464\pm.015$ $.442\pm.006$ H $.437\pm.031$ $15/32$ max. $.469\pm.031$ $\%$ max.J $.176\pm.010$ $.176\pm.010$ $.176\pm.010$ K $.625\pm.010$ $.625\pm.010$ $.625\pm.010$ L $.970\pm.006$ $1.187\pm.010$ $.656\pm.010$ R ₁ $.656\pm.010$ $.845\pm.010$ $.845\pm.010$	E D D C ON MANUAL RESET ONLY	G		A R2 R1 B B C C C C C C C C C C C C C C C C C		
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L .970±.006 1.187±.010 R ₁ .656±.010 .656±.010	J		.176±.010		.176±.010	
R ₁ .656±.010 .656±.010	К		.625±.010		.625±.010	
	L		.970±.006		$1.187 \pm .010$	
R ₂ .845±.010 .845±.010	R ₁		.656±.010		.656±.010	
	R ₂		.845±.010		.845±.010	

Types MY, CY and BY

 † 1.232 ±.010 for manual reset version.

Types MW and CW

Texas Instruments provides customer assistance in varied technial areas. Since TI does not possess full access to data concerning all of the uses and applications of customers' products, responsibility is assumed by TI neither for customer product design nor for any infringements of patents or rights of others which may result from TI assistance.

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